

#### CAN bus for UAV and robots

# What is UAVCAN

- CAN bus for UAV
- Consistent ecosystem
- Open standard
- MIT-licensed reference implementation
- Advanced features

# Core design goals

- Publish-Subscribe & Request-Response
- Democratic network
- Long messages
- Redundancy
- Simplicity



### DAS DANISH AVIATION SYSTEMS







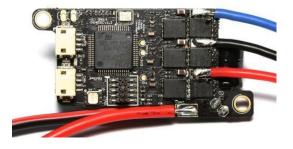


# Now and future of UAVCAN

- Specification is stable
- Last RFC next month
- Release mid 2015
- Feedback is welcome <u>uavcan.org/contact</u>

## A use case - PX4ESC

- Feedback and diagnostics via UAVCAN
- Advanced motor control
- Redundancy
- Open hardware
- BSD-licensed firmware





# Now and future of PX4ESC

- It's flying
- Release in two months
- More at <a href="mailto:pixhawk.org/firmware/px4esc">pixhawk.org/firmware/px4esc</a>